

# Data assimilation for NWP at Météo-France: current status and plans towards an increased usage of active instruments

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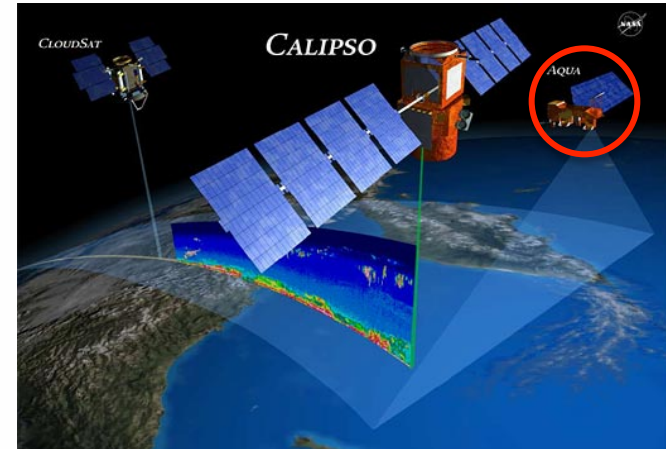
CALIPSO-CLOUDSAT 10 year progress assessment and path forward 8-10 June 2016

\*with contributions from C. Augros,  
H. Bénichou, M. Borderies, N. Boullot, P. Chambon

# Purpose of this presentation

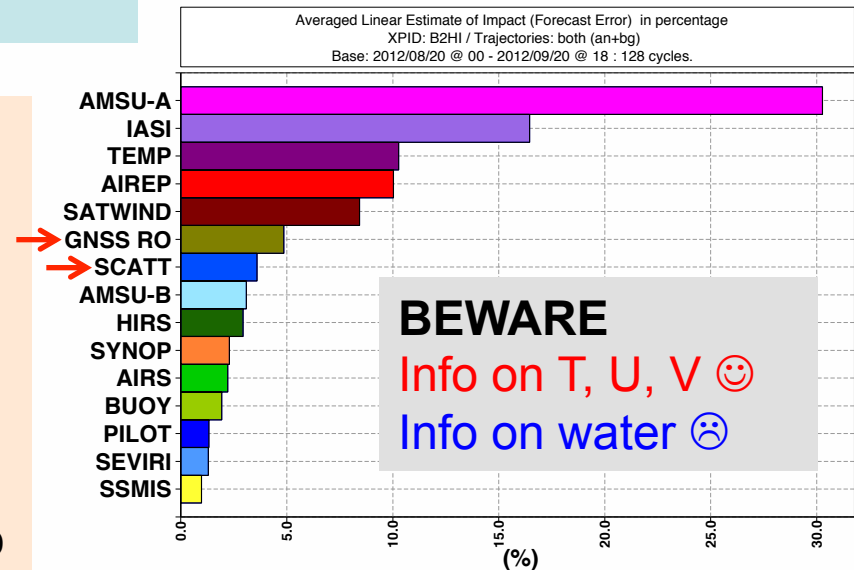
Explain :

- > the current usage of observations for NWP with an emphasis on satellite data (> 90 % in global systems)
- > why the use of active instruments is currently challenging (visible, IR, MW) in NWP despite providing complementary and valuable information on the atmosphere
- > why rapid progress is expected in the coming years



*What are currently the most « useful » observing systems for global NWP ?*

- > **AMSU-A**: microwave 55 GHz, several instruments, weakly affected by clouds, low Ne $\Delta$ T, info on T
- > **IASI**: infra-red 15  $\mu$ m-> 4  $\mu$ m, many channels (cloud detection), low Ne $\Delta$ T, info on T and WV



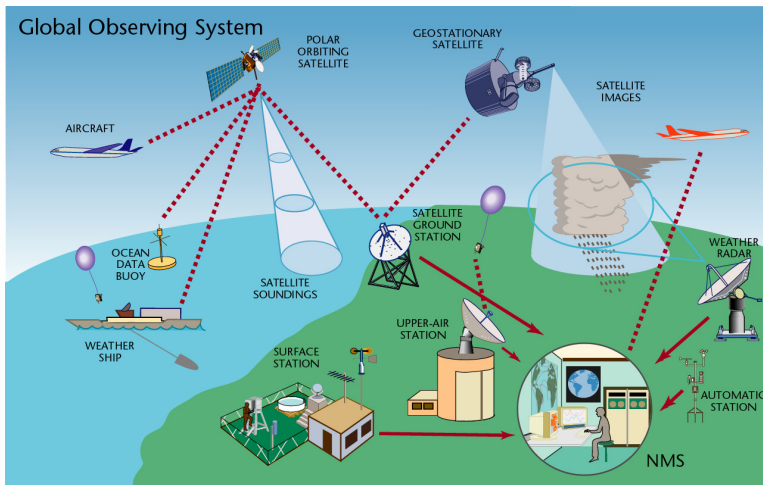
# Outline

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- Generalities about observations for data assimilation
- On the use of observations for NWP at Météo-France
- Activities on radar data assimilation
- Plans towards increased usage of active instruments

# Preamble

- **Observations for NWP:** used to create an accurate model *initial condition* to provide an accurate forecast
- **Data Assimilation:** Statistical optimal combination between available observations and a short-range forecast (background or first-guess)
- **DA important aspects:**
  - Optimality => knowledge of random and systematic errors (biases)
  - Importance of quality controls and model capacity to simulate the observations (observation operator) => reject « useless » observations



Variables of interest:

Current: mass, temperature, wind, water vapour

Future: soil moisture, condensed water, atmospheric composition, aerosols, ...

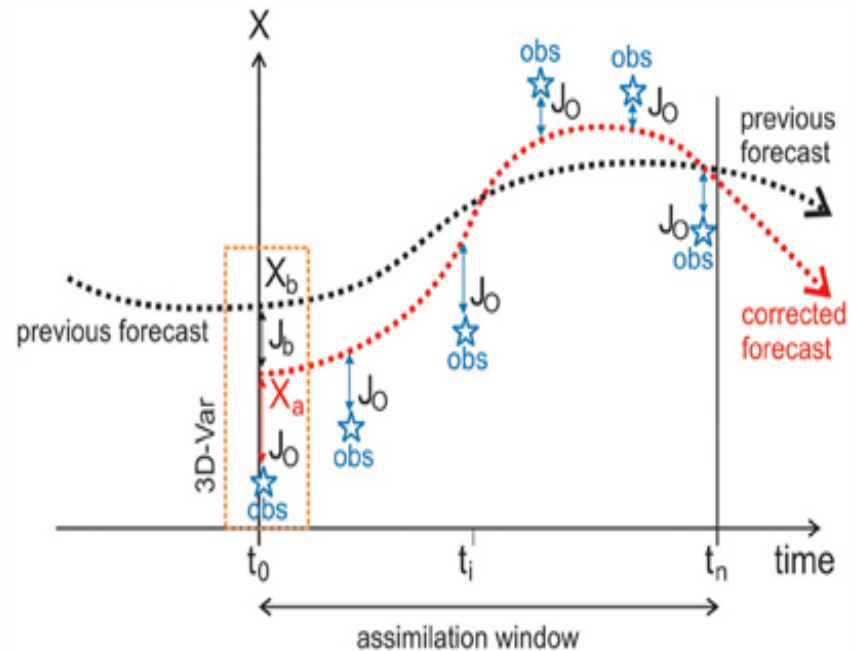


# Variational data assimilation

Mathematical formulation: cost-function to minimize

$$J(x) = \frac{1}{2}(x - x_b)^T B^{-1}(x - x_b) + \frac{1}{2}[y - H(x)]^T R^{-1}[y - H(x)]$$

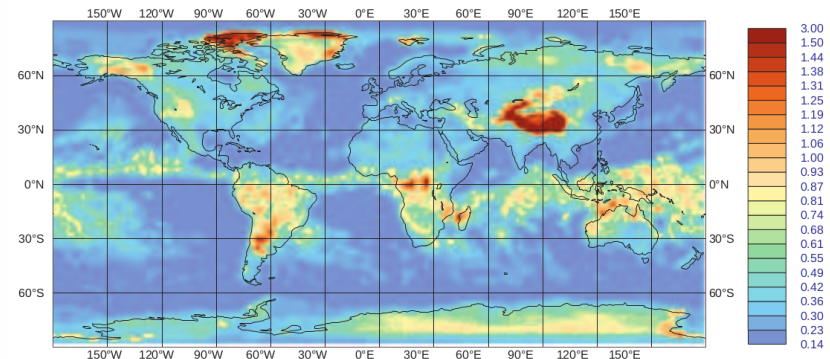
- $x$  = state vector (temperature, wind components, surface pressure, water vapour content)
- $x_b$  = background (short-range forecast)
- $y$  = available observations
- $H$  = observation operator
- $B$  = background error covariance matrix
- $R$  = observation error covariance matrix



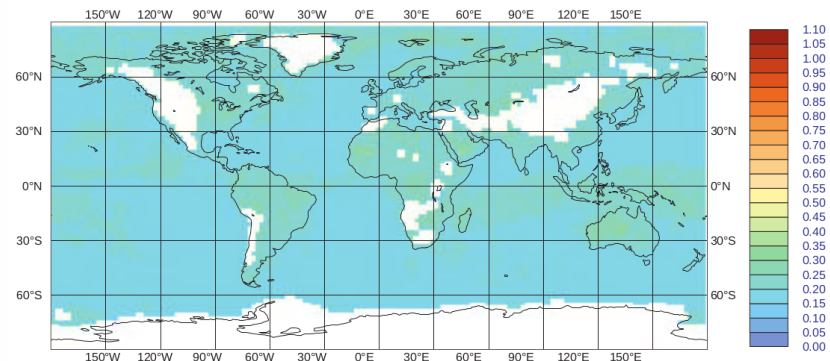
# Observations for DA in NWP : requirements

- **Accurate model to simulate (rapidly) the observation:** observation too far from the model => problem either with the observation or with the model – observations closer to the measurement should be favored (L1 vs L2)
- **Accurate and complementary observations:** accurate enough and numerous (in time and/or space) and should complement existing observing systems (redundancy can be useful for improving resilience)
- **Near-real time availability:** less than 3 hours after the measurement
- **Unbiased and uncorrelated:** bias corrections – data sampling

Observation minus model



All data : AMSU-A Ch5

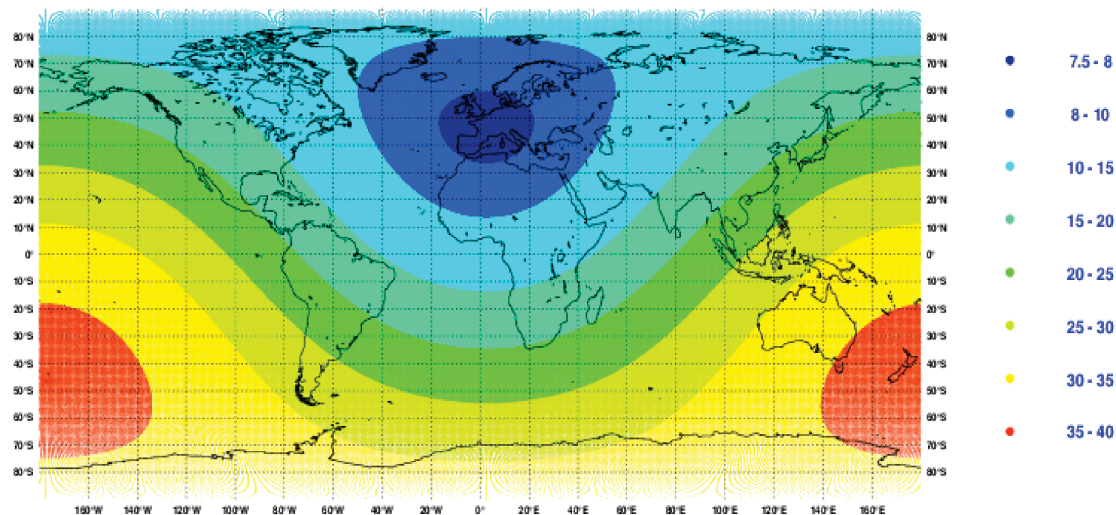


Data for assimilation

*Remark : for AMSU-A in clear sky OmB close to Ne $\Delta$ T (0.3 K)*

# Global model ARPEGE

Spectral model with variable resolution : T<sub>L</sub>1198c2.2L105  
(resolution from 7.5 km to 36 km, 105 levels from 10 m to 0.1 hPa)  
Forecasts up to 104 hours

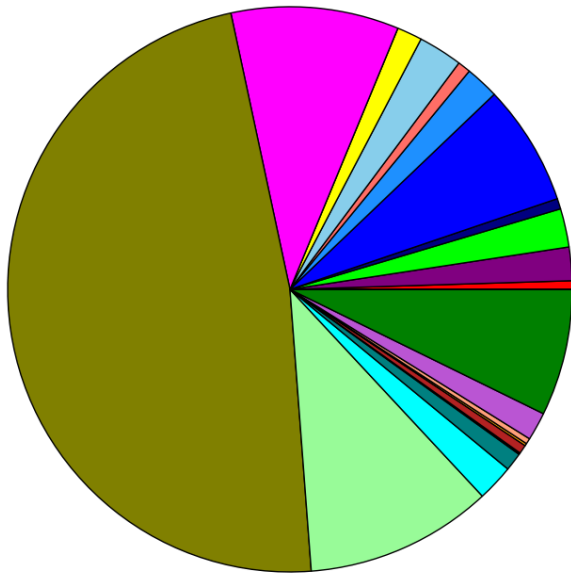


Moist physical processes : prognostic large-scale precipitation scheme with explicit microphysics for 4 species (Lopez, 2002) and diagnostic moist convection scheme based on mass-flux (Bougeault, 1985)

Data assimilation system : 4D-Var (6-h window and 30 min time-slots) + ensemble data assimilation system (background error statistics)

# Partition by observation types

Proportions des nombres d'observations utilisées par type d'obs  
 analyses cut-off long - ARPEGE metropole dbl  
 observations conventionnelles et satellites  
 cumul du nombre d'observations utilisées sur la période 2015120100 - 2015120118 : 20675304



GPS ground	0.49%	SSMIS	1.44%	SYNOP/SYNOR/RADOME	0.50%
GPS sat	1.91%	GMI	0.00%	SHIP	0.14%
SATOB	2.20%	AIRS	9.60%	PILOT/PRF	0.32%
ATOVS HIRS	0.60%	IASI	47.84%	TEMP	1.61%
ATOVS AMSU-A	6.93%	CRIS	10.73%	AIRCRAFTS	7.25%
ATOVS AMSU-B	1.92%	GEORAD	2.10%	RADAR Vr	0.00%
SAPHIR	0.74%	SCATT	1.04%	RADAR Hur	0.00%
ATMS	2.53%	BUOY	0.10%	BOGUS	0.00%

Total number of daily data assimilated  
 (4 analyses per day) :  
**20.6 millions**

IR sounders -> **IASI 48 % + AIRS 10 % + CrIS 11 % => 69 %**  
**MW sounders/imagers : 14 %**

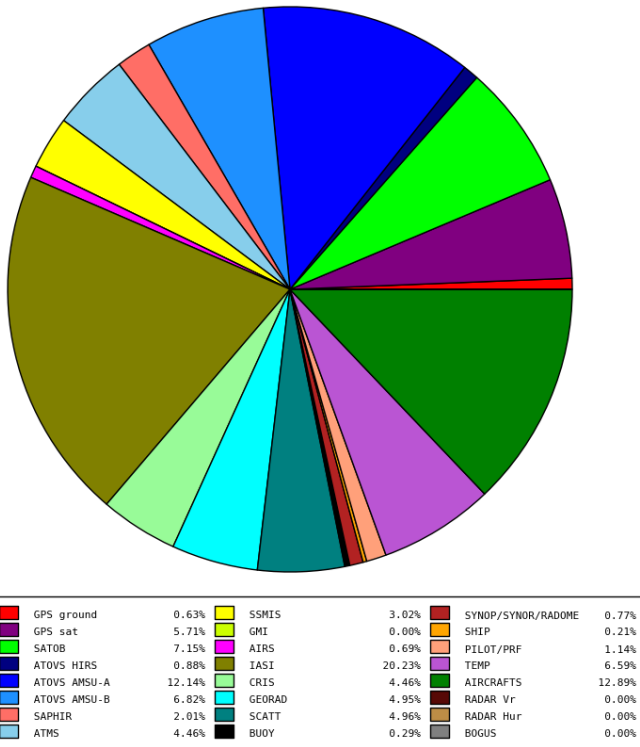
GPS- RO : 2 %  
 SCAT winds : 1 %  
 SATOB winds : 2 %

Aircraft data : 7 %  
 TEMP+PILOT : 2 %

ARPEGE Model – 01/12/2015

# Information content : DFS

Part des DFS par type d'obs  
analyses cut-off long - ARPEGE metropole dbl  
observations conventionnelles et satellites  
cumul du DFS sur la période 2015120100 - 2015120118 : 481780



DFS : depends upon the number of observations, the observation accuracy, the projection on the variables to analyse (T,q,U,V,Ps)

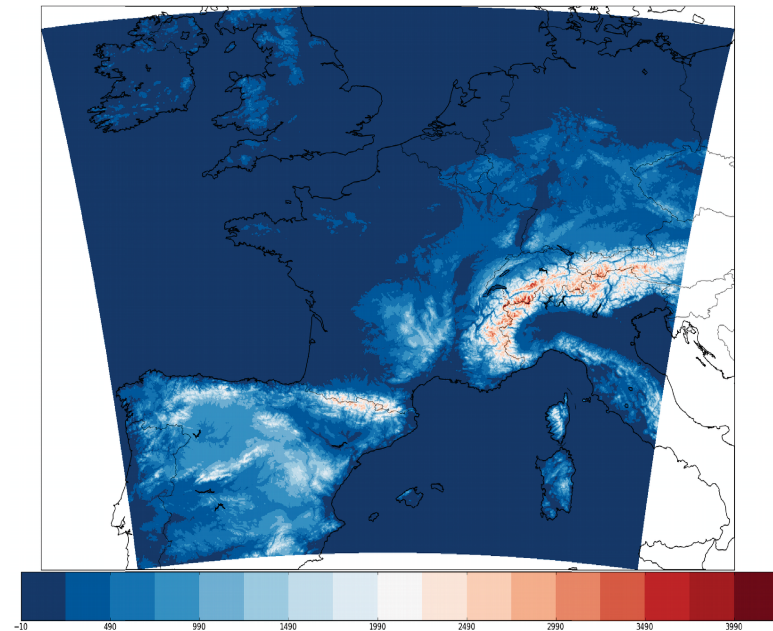
**MW imagers/sounders : 28 %**  
**IASI IR sounder : 20 %**

Aircraft data: 12 %  
TEMP+PILOT : 8 %  
GPS- RO : 6 %  
SCAT winds : 5 %  
SATOB winds : 7 %

DFS (Degree of Freedom for Signal)  
: capacity of an observing system to reduce the a-priori information

# Regional model AROME

- Spectral limited area non-hydrostatic model with explicit moist convection (since 12/2008) => hydrometeors as prognostic variables (mass concentration)
- Horizontal resolution : 1.3 km
- 90 vertical levels (from 5 m up to 10 hPa)
- 3D-Var assimilation (1-h window)
- Observing system : same as ARPEGE (+) 5 SEVIRI/MSG radiances (with  $T_s$  inversion) (+) radar DOW and Z (RH)
- Forecast range : up to 42 hours





# Observations in AROME 3D-Var

IASI  
 AIRCRAFTS  
 SURFACE  
 RADARS  
 SEVIRI  
 ATOVS  
 TEMP

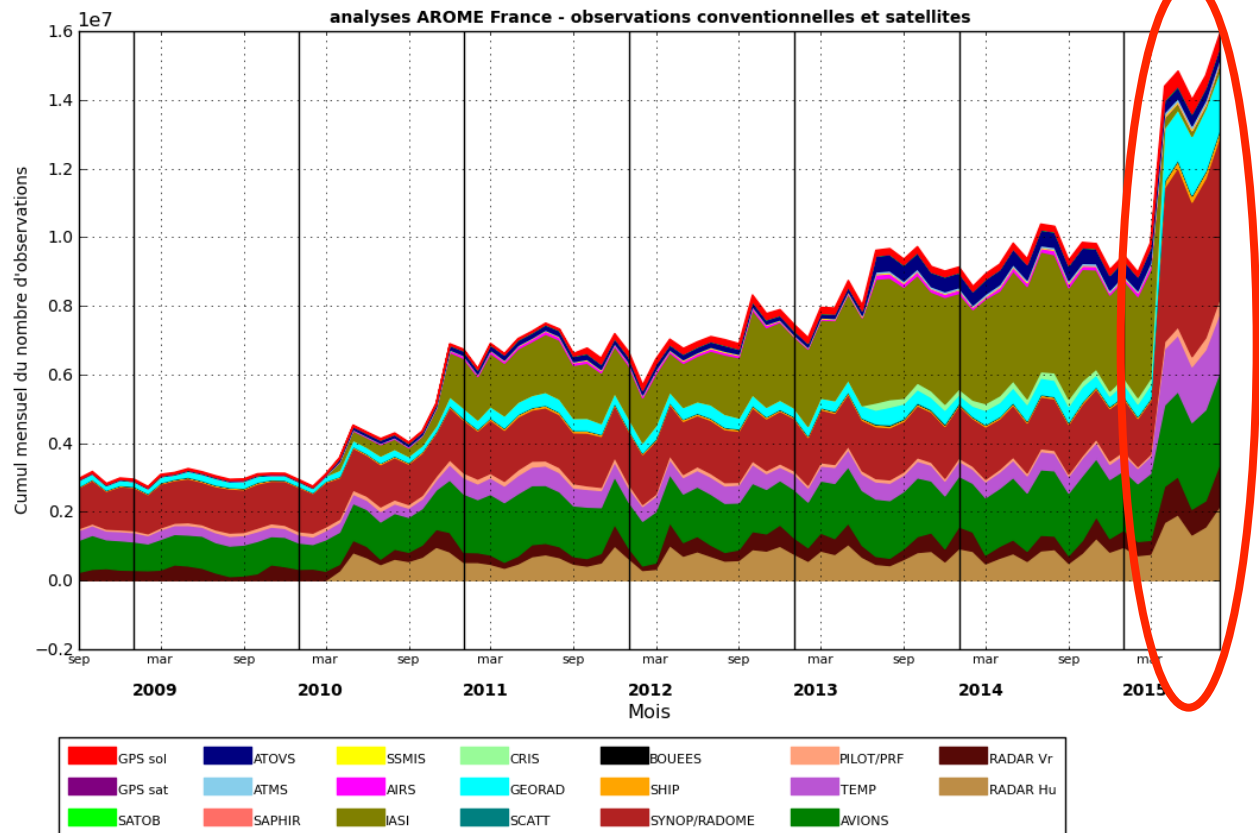
At mesoscale (mid-latitudes):

ground based  
 and conventional  
 obs

>> satellite data

Obs at high temporal  
 availability

Evolution des cumuls mensuels de nombre d'observations utilisées par type d'observation



DirOP/COMPAS 29-septembre-2015

# Simulation of polarimetric radar data (1)

One moment cloud scheme : ICE3 with 6 water species (water vapor, cloud water, rain water, graupels, dry snow and pristine ice)

PSD : Exponential for rain, snow and graupel, generalized Gamma for cloud water and pristine ice

Densities are given by mass-diameter relationships  $m = aD^b$

What we would like to simulate :

- horizontal reflectivity  $Z_{hh}$
- differential reflectivity  $Z_{dr}$
- differential phase  $\Phi_{dp}$
- specific differential phase  $K_{dp}$
- co-polar correlation coefficient  $\rho_{hv}$

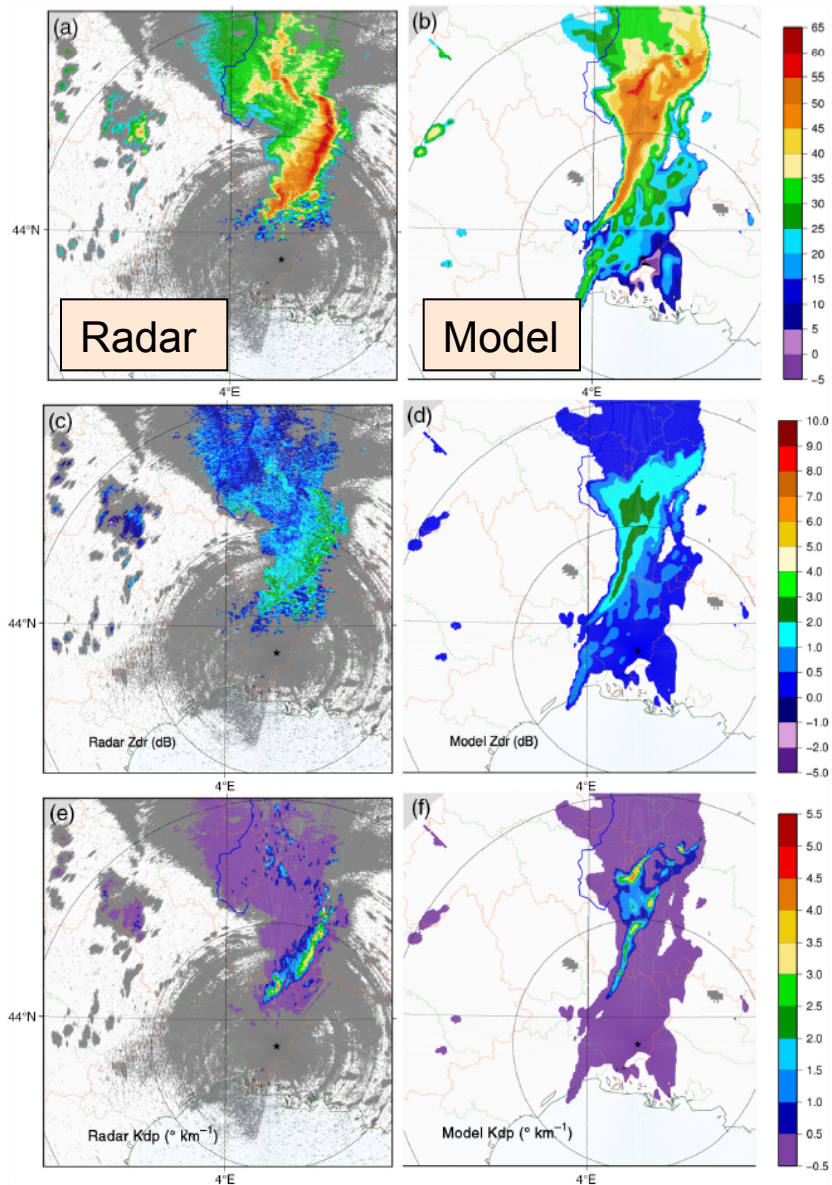
What needs to be specified with some level of arbitrariness:

- raindrop shape : axis ratio  $r = f(D_{eq})$
- dielectric function for snow and graupels (Maxwell-Garnett)
- dielectric properties for melting graupels





# Simulation of polarimetric radar data (2)



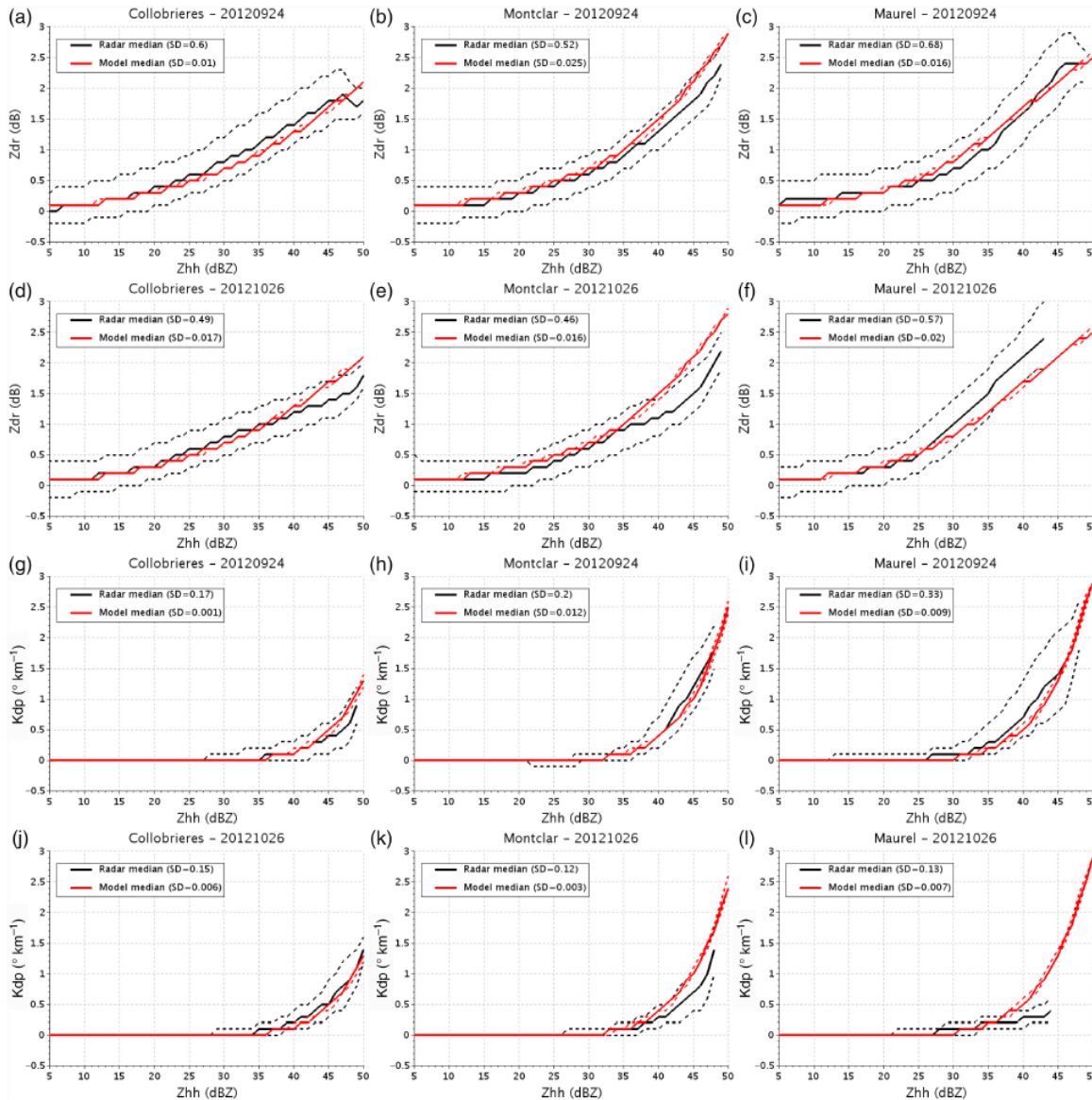
$Z_{hh}$

$Z_{dr}$

$K_{dp}$

Augros et al. (2015)  
QJRMS

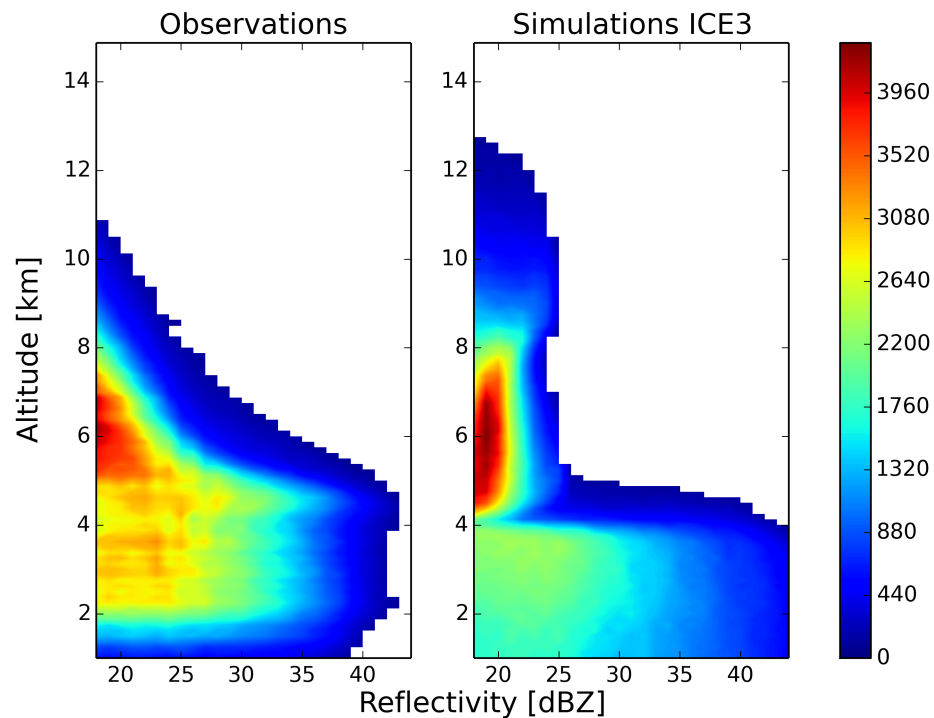
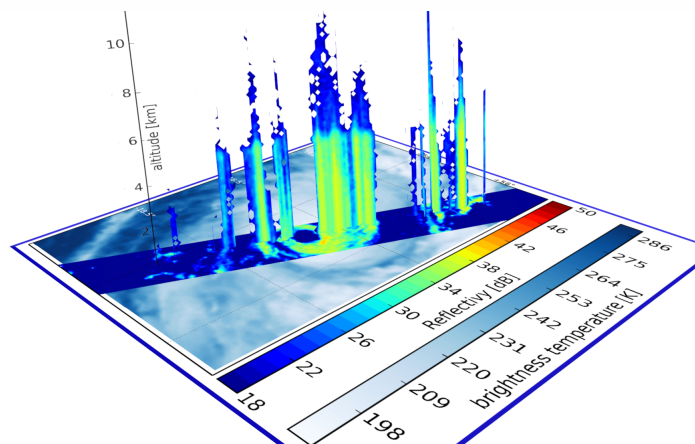
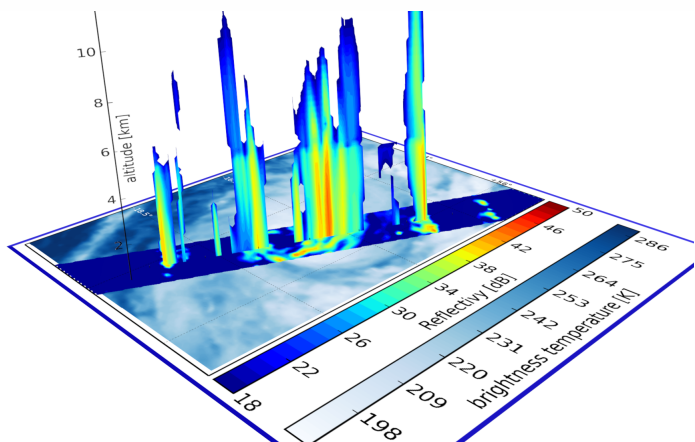
# Simulation of polarimetric radar data (3)



$Z_{dr} = f(Z_{hh})$   
 $K_{dp} = f(Z_{hh})$   
**MODEL**  
**RADAR**  
 Lack of variability in the model  
 -> one moment scheme

Augros et al. (2015)  
QJRMS

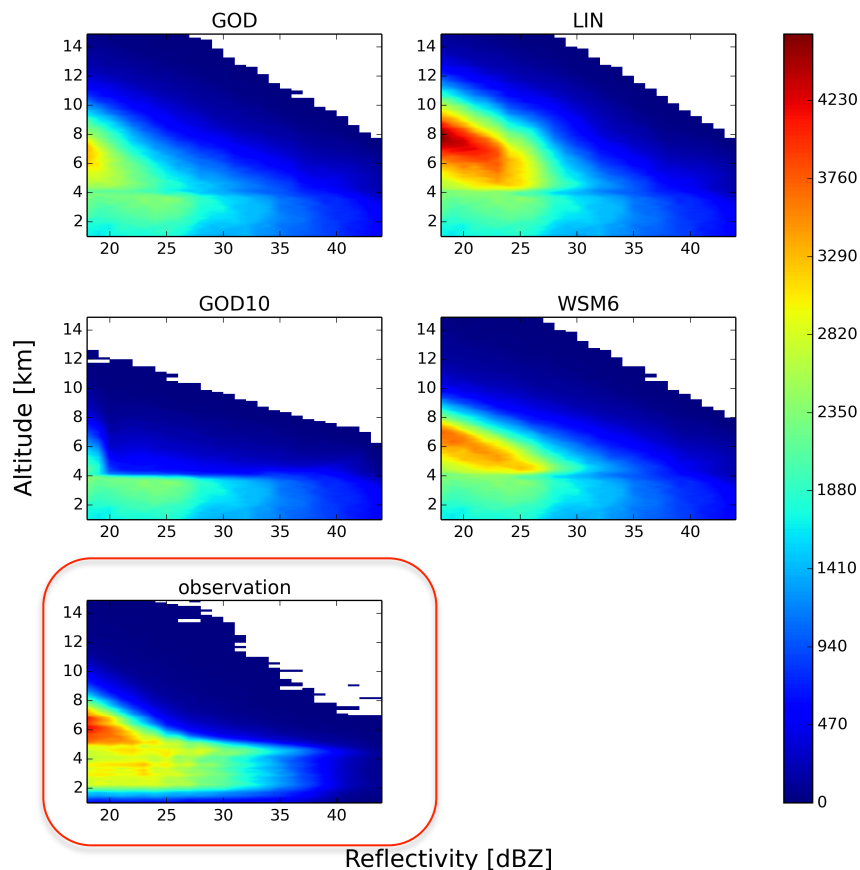
# Simulation of GPM DPR with AROME (1)



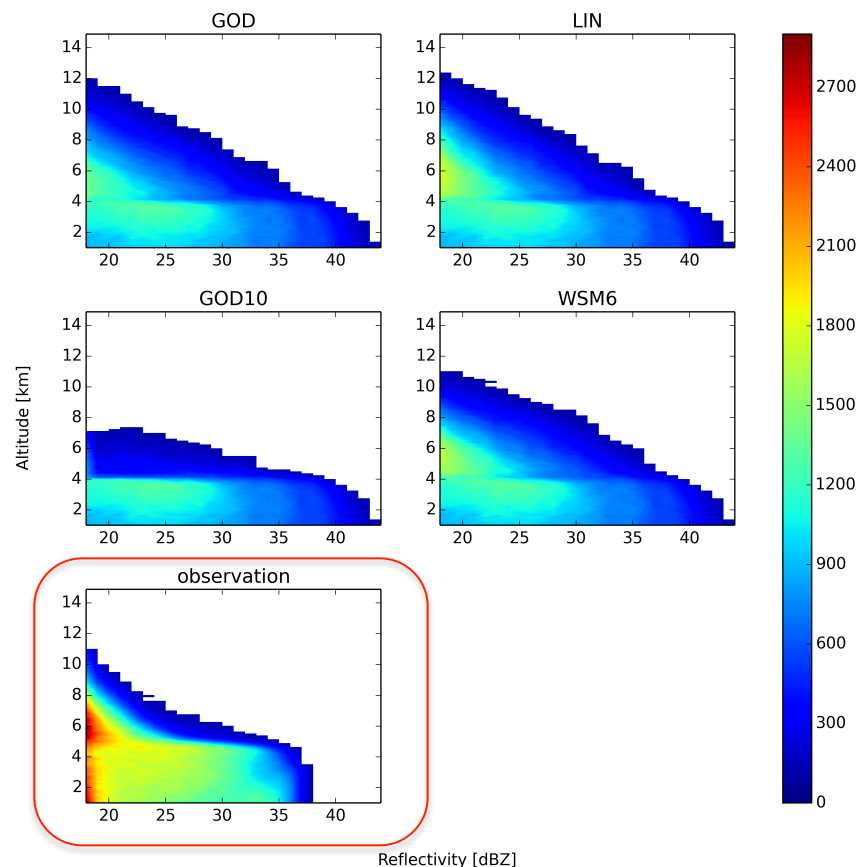
2D histograms (10 days) of DPR reflectivities in Ku band using microphysics consistent with ICE 3 in SDSU radar simulator

# Simulation of GPM DPR with AROME (2)

## Ku band



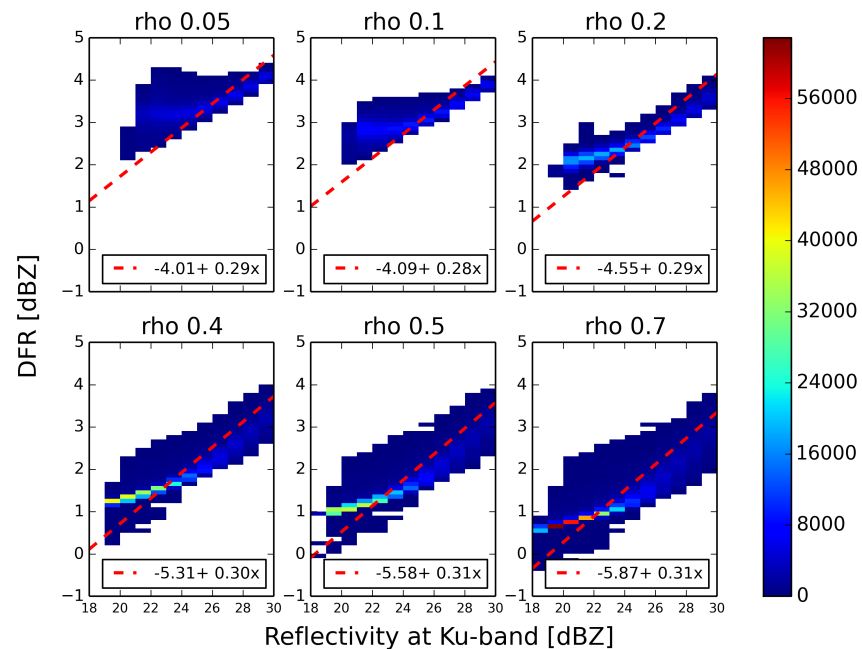
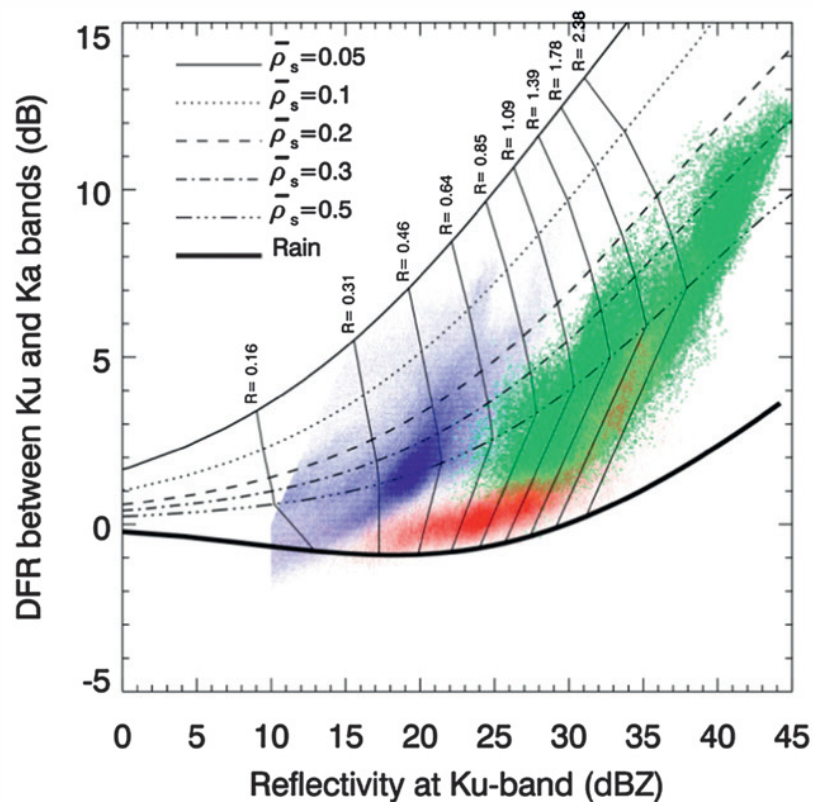
## Ka band



GOD : Tao (2003)  
GOD10 : improved GOD

LIN : Lin et al. (1983)  
WSM6: Hong et al. (2004)

# Simulation of GPM DPR with AROME (3)



Use of the Dual Frequency Ratio to constrain the snow density specification in the radar simulator



# Data assimilation of active sensors

- **Current status:** spaceborne (scatterometers : C and Ku band radars; GNSS-RO : L-band signals) + ground based (weather radars : C, S and X band; wind profilers)
- **Drawbacks:** the raw signal (backscatter coefficient, reflectivity) is converted into a meteorological quantity before assimilation
- **Explanation:** Lack of knowledge in the NWP model on the physical content of the signal (cloud microphysics, sea state) => observation operator
- **Future spaceborne instruments :** ADM-AEOLUS (Doppler wind lidar ; use of L2 products), EarthCare (cloud radar and lidar ; 1D +4D-Var at ECMWF)
- **Difficulties for DA:** polar orbiting satellites with nadir viewing, rather crude description of clouds and aerosols to simulate observations (regional vs. global systems) – but still very useful for model validation (preliminary step before DA)

# Conclusion and future activities

- **Interest:** detailed vertical structure on complementary meteorological variables + high temporal frequency of ground based instruments (convective scale DA – nowcasting)
- **Expected model and data assimilation improvements :**
  - More realistic description of cloud microphysics (2 moment schemes) with aerosol interactions (nucleation, scavenging, ...)
  - Coupled modelling systems with atmosphere, ocean, land surface, sea state, chemistry, ...
  - Development of ensemble data assimilation including new prognostic variables (clouds, precipitation, atmospheric composition) with associated background error statistics
- **Requirements :**
  - Development of accurate and efficient observation operators - need to explore the short-wave spectrum (IR + solar)
  - Improved handling of model and observation errors (biases, ...)
  - Space based instruments with a wide swath ?

Thank you for your attention !



**METEO  
FRANCE**